The Series WE34 incorporates a full port 3-way flanged SS ball valve for great flow rates with minimal pressure drop. The valve features a blowout-proof stem for added safety, reinforced PTFE seats and seals for longer life, and a 316 SS (ASTM CF8M) ball for better performance. Actuators are direct mounted creating a compact assembly for tight spaces. Limit switches are able to be mounted directly to the valves allowing for remote position indication.

The Series WE34 can be configured with either an electric or pneumatic actuator. Electric actuators are available in weatherproof or explosion-proof, a variety of supply voltages and two-position or modulating control. Two-position actuators use the supply voltage to drive the valve open or closed, while the modulating actuator accepts a 4 to 20 mA input for valve positioning. Actuators feature thermal overload protection and permanently lubricated gear train.

The pneumatic double acting actuator uses an air supply to drive the valve open and closed. The actuator has two supply ports, with one driving the valve open and the other driving the valve closed. Spring return pneumatic actuators use the air supply to open the valve, and internally loaded springs return the valve to the closed position. Also available is the SN solenoid valve to electrically switch the air supply pressure between the air supply ports for opening and closing the valve. Actuators are constructed of anodized and epoxy coated aluminum for years of corrosion free service.

**SPECIFICATIONS**

**VALVE**

**Service:** Compatible liquids and gases.

**Body:** 3-way.

**Line Sizes:** 1/2 to 3”.

**End Connections:** 150# ANSI flange.

**Pressure Limits:** 20” Hg to 275 psi (-0.7 to 19 bar).

**Wetted Materials:**
- Body and ball: 316 SS (CF8M);
- Stem: 316 SS;
- Seat: RTFE/PTFE;
- Washer and Packing: PTFE.

**Temperature Limits:** -20 to 392°F (-29 to 200°C).

**Other Materials:**
- O-ring: Fluoroelastomer;
- Handle: 304 SS;
- Washer: 301 SS;
- Stem Nut, Locking Device, Gland Ring: 304 SS;
- Handle Sleeve: PVC.

**ACTUATORS**

**Pneumatic “DA” and “SR” Series**

**Type:** DA series is double acting and SR series is spring return (rack and pinion).

**Normal Supply Pressure:**
- DA: 40 to 115 psi (2.7 to 7.9 bar);
- SR: 80 psi (5.5 bar).

**Maximum Supply Pressure:** 120 psi (8.6 bar).

**Air Connections:**
- DA01: 1/8” female NPT;
- DA02 to DA08: 1/4” female NPT;
- SR03 to SR09: 1/4” female NPT.

**Housing Material:** Anodized aluminum body and epoxy coated aluminum end caps.

**Temperature Limits:** -40 to 176°F (-40 to 80°C).

**Accessory Mounting:** NAMUR standard.

**Electric “TD” and “MD” Series**

**Power Requirements:** 110 VAC, 220 VAC, 24 VAC or 24 VDC (MD models not available in 24 VDC).

**Power Consumption:** See page 8.

**Cycle Time (per 90°):**
- TD01: 4 s;
- MD01: 10 s;
- TD02 and MD02: 20 s;
- TD03 and MD03: 30 s;
- TD04 and MD04: 30 s.

**Duty Rating:** 85%.

**Enclosure Rating:** NEMA 4X (IP67).

**Housing Material:** Powder coated aluminum.

**Temperature Limits:** -22 to 140°F (-30 to 60°C).

**Electrical Connection:** 1/2” female NPT.

**Modulating Input:** 4 to 20 mA.

**Standard Features:** Manual override, position indicator, and TD models come with two limit switches.

**Electric “TI” and “MI” Series**

**Power Requirements:** 110 VAC, 220 VAC, 24 VAC or 24 VDC.

**Power Consumption:** See page 8.

**Cycle Time (per 90°):**
- TI01 and MI01: 2.5 s;
- TI02 and MI02: 5 s;
- TI03 and MI03: 5 s;
- TI04 and MI04: 10 s;
- TI05 and MI05: 15 s;
- TI08 and MI08: 12 s.

**Duty Rating:**
- Two-Position:
  - TI01-TI07: 25%;
  - TI08: 100%.
- Modulating:
  - MI01-MI07: 75%;
  - MI08: 100%.

**Enclosure Rating:** NEMA 7.

**Housing Material:** Powder coated aluminum.

**Temperature Limits:** -40 to 140°F (-40 to 60°C).

**Electrical Connection:** 1/2” female NPT.

**Modulating Input:** 4 to 20 mA.

**Standard Features:** Position indicator and two limit switches.
### POPULAR MODELS

<table>
<thead>
<tr>
<th>Size</th>
<th>Cv (gal/min)</th>
<th>Hand Operated Model</th>
<th>Double Acting Pneumatic Model</th>
<th>Spring Return Pneumatic Model</th>
<th>NEMA 4X Two Position Electric (110 VAC) Model</th>
<th>NEMA 4X Modulating Electric (110 VAC) Model</th>
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### VALVE BILL OF MATERIALS

1. **Body**
   - ASTM A351-CF8M

2. **Cap**
   - PTFE

3. **Ball**
   - SUS 304

4. **Ball Seat**
   - PTFE

5. **Stem**
   - PEEK + PTFE

6. **Gasket**
   - SUS 304

7. **O-Ring**
   - Fluoroelastomer

8. **Pack**
   - PTFE

9. **Thrust Washer**
   - SUS 304

10. **Spring Washer**
    - 1.75

11. **Stop Nut**
    - 1.75

12. **Stop Washer**
    - 1.75

13. **Stop Pin**
    - 1.75

14. **Handle Washer**
    - 1.75

15. **Locking Device**
    - 1.75

16. **Handle**
    - 1.75

17. **Handle Cover**
    - PVC

### Model Number Specification

<table>
<thead>
<tr>
<th>Model Number</th>
<th>Size</th>
<th>ØA (in)</th>
<th>ØA1 (in)</th>
<th>ØB (in)</th>
<th>ØF (in)</th>
<th>G (in)</th>
<th>M</th>
<th>N</th>
<th>ØLF (in)</th>
<th>ØL (in)</th>
<th>ØH (in)</th>
<th>W (in)</th>
<th>ØD1 (in)</th>
<th>ØD2 (in)</th>
<th>ISO</th>
<th>S (in)</th>
<th>ØRa (in)</th>
<th>ØRb (in)</th>
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</table>

### Handle Design

- For 1-1/4˝ - 4˝

### Specification

- **Model Number**
- **Size**
- **ØA (in)**
- **ØA1 (in)**
- **ØB (in)**
- **ØF (in)**
- **G (in)**
- **M**
- **N**
- **ØLF (in)**
- **ØL (in)**
- **ØH (in)**
- **W (in)**
- **ØD1 (in)**
- **ØD2 (in)**
- **ISO**
- **S (in)**
- **ØRa (in)**
- **ØRb (in)**
- **Port**
- **M1**
- **Cv (gal/min)**

### Notes

- **ØA** is the outer diameter of the body.
- **ØA1** is the inner diameter of the body.
- **ØB** is the outer diameter of the body flange.
- **ØF** is the outer diameter of the body flange.
- **G** is the thickness of the gasket.
- **M** is the number of threads.
- **N** is the number of threads.
- **ØLF** is the length of the body.
- **ØL** is the length of the body.
- **ØH** is the height of the body.
- **W** is the width of the body.
- **ØD1** is the outer diameter of the body at the flange.
- **ØD2** is the outer diameter of the body at the body.
- **ISO** is the international standard.
- **S** is the size of the piston.
- **ØRa** is the outer diameter of the piston.
- **ØRb** is the inner diameter of the piston.
- **Port** is the port size.
- **M1** is the material.
- **Cv (gal/min)** is the flow rate.

### Diagram

- **Valve**
- **Model Number**
- **Size**
- **ØA (in)**
- **ØA1 (in)**
- **ØB (in)**
- **ØF (in)**
- **G (in)**
- **M**
- **N**
- **ØLF (in)**
- **ØL (in)**
- **ØH (in)**
- **W (in)**
- **ØD1 (in)**
- **ØD2 (in)**
- **ISO**
- **S (in)**
- **ØRa (in)**
- **ØRb (in)**
- **Port**
- **M1**
- **Cv (gal/min)**

### Table

- **Model Number**
- **Size**
- **ØA (in)**
- **ØA1 (in)**
- **ØB (in)**
- **ØF (in)**
- **G (in)**
- **M**
- **N**
- **ØLF (in)**
- **ØL (in)**
- **ØH (in)**
- **W (in)**
- **ØD1 (in)**
- **ØD2 (in)**
- **ISO**
- **S (in)**
- **ØRa (in)**
- **ØRb (in)**
- **Port**
- **M1**
- **Cv (gal/min)**
PNEUMATIC ACTUATOR
Note: For optimal operation, pneumatic actuators should be run with a supply of clean, lubricated air.

Spring Return Actuator Operation
Air to PORT 2 (the right hand port) causes the actuator to turn counter clockwise (CCW). Loss of air to PORT 2 causes air to exhaust and the actuator turns clockwise (CW). This is the FAIL CLOSE operation.

Double Acting Actuators Operation
Air to PORT 2 (the right hand port) causes the actuator to turn counter clockwise (CCW). Air to PORT 1 (the left hand port) causes the actuator to turn clockwise (CW).

Pneumatic Actuator Maintenance
Routine maintenance of pneumatic actuator:
• Keep the air supply dry and clean
• Keep the actuator surface clean and free from dust
• Periodic checks should be done to make sure all fittings are tight
• Pneumatic actuators are supplied with lubrication to last the entire life span of the actuator under normal operating conditions.

The outer surface of the pneumatic actuator should be clean to avoid friction or corrosion. All fittings and connections should be tight to prevent leaks during operation. Check the bolts mounting the valve to the actuator to make sure they have not come loose during shipping or installation. Make sure the valve and actuator are not rubbing or jamming against other components during operation. The actuator should be inspected annually to make sure all fittings and bolts are tight and nothing has come loose during operation.

Disassembling Pneumatic Actuators
WARNING Before beginning disassembly, ensure that the air supply to the actuator has been disconnected, all accessories have been removed, and that the actuator has been disassembled from the valve. 1. Loosen the end cap fasteners (22) with a wrench (size varies depending on actuator model). On the spring return actuator, alternate 3 to 5 turns on each fastener until the springs are completely decompressed. Use caution when removing the cap since the springs are under load until the fasteners are fully extended. 2. Remove the pinion snap ring (10) with a lock ring tool. The indicator (7) may now be removed. 3. Turn the pinion shaft (2) counter clockwise until the pistons are at the full end of travel. Disengage the pistons (11) from the pinion. (NOTE: Low pressure air--3 to 5 psi MAXIMUM--might be required to force the pistons completely from the body.) Note the position of the pistons before removing them from the actuator body. 4. Remove the pinion through the bottom of the actuator. The actuator is now completely disassembled.

Pneumatic Actuators Bill of Materials

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<th>Part Number</th>
<th>Quantity</th>
<th>Part Name</th>
<th>Material</th>
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<td>3</td>
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Failures | Inspection Items | Corrective Action
---|------------------|------------------|
Pneumatic actuator won't operate | 1. Check the solenoid valve. Is the coil burnt out or is the solenoid spool? | 1. Replace the solenoid valve coil or remove debris. |
| 2. The actuator will not move because of debris in the gears. | 2. Disassemble the actuator, clean the debris and reassemble the actuator. |
| 3. The pneumatic line to the actuator is distorted or smashed. | 3. Replace pneumatic line to the actuator. |
| 4. The pneumatic line is frozen because of low temperatures and moisture. | 4. Warm the pneumatic lines and remove moisture from supply lines. |
Pneumatic actuator runs slowly | 1. The air supply pressure is insufficient. | 1. Increase the air supply pressure and look for leaks in the supply pressure pipeline. |
| 2. Are other pneumatic devices consuming the air required for the actuator to operate? | 2. Increase the air supply or reduce the number of devices operating at the same time. |
| 3. The pneumatic actuator is undersized for the application. | 3. Replace the actuator with a larger actuator. |

Reassembling Pneumatic Actuators

**WARNING** Be sure the actuator surfaces are free of debris and scratches before reassembling.

1. Apply a light film of grease to all O-rings and the pinion before replacing. 2. Put the pinion (2) back through the actuator with the flats of the pinion shaft running parallel with the body. 3. When reassembling the actuator, make sure that the piston racks are square to the actuator body and returned to their original orientation. (NOTE: The normal operation of all spring return pneumatic actuators is FAIL CLOSED. To change the orientation to FAIL OPEN, rotate the racks 180° to create a reverse operation. 4. When replacing springs in a spring return actuator, ensure that the springs are replaced in their identical position in the end cap from which they were removed. (NOTE: In some circumstances, you might want to change the standard 80 pound spring set to fit your application and available air pressure.) 5. Seal the end caps with a petroleum lubricant and bolt to actuator body. 6. Check the seal of the actuator by covering seal areas (pinion, end caps) with soapy water and using low pressure air to the actuator to ensure that no bubbles are produced.
### ELECTRIC ACTUATORS

**Electric Installation**

1. Operate valve manually and place in the open position.
2. Remove any mechanical stops the valve might have. (DO NOT REMOVE ANY PARTS NECESSARY FOR THE PROPER OPERATION OF THE VALVE, SUCH AS THE PACKING GLAND, PACKING NUT, ETC.)
3. Ensure that the actuator output shaft and valve stem are aligned properly. If they are not, operate the valve manually until they are correct.
4. Remove actuator cover.
5. Bring power to the actuator. CAUTION: Make sure power is OFF at the main box.
6. Wire the actuator per the diagram attached to the inside of the cover. Special actuators (those with positioner boards, etc.) will have diagrams enclosed inside the cover.
7. Securely tighten bolts used to mount the actuator to a mounting bracket or directly to the valve mounting pad if it is ISO5211 compliant.
8. Cycle the unit several times and check the open and closed positions of the valve. Cams are pre-adjusted at the factory; due to the variety of valve designs and types however, slight adjustments might be required.
9. Replace cover and tighten screws.

### To Set The Open Position

1. Cycle the valve to the open position by applying power to terminals. The top cam and switch control this position. In the open position, the set screw in the top cam will be accessible.
2. If the valve is not open completely:
   - A. Slightly loosen the set screw on the top cam.
   - B. Rotate the cam clockwise (CW) by hand until the switch makes contact. Contact is made when a slight click can be heard. By making incremental CW movements of the bottom cam, the valve can be positioned precisely in the desired position.
   - C. When the top cam is set, tighten the set screw securely.
3. If the valve opens too far:
   - A. Apply power to terminals. This will begin to rotate valve CW. When valve is fully open and in the exact position desired, remove power from actuator.
   - B. Loosen the set screw in the top cam.
   - C. Rotate the top cam counterclockwise (CCW) until the switch arm drops off the round portion of the cam onto the flat section. A slight click can be heard as the switch changes state.
   - D. Continue applying power to terminals until valve is in the desired position.

### To Set The Closed Position

1. Apply power to terminals to move the valve toward the closed position. The bottom cam and switch control the closed position. In the closed position, the set screw in the bottom cam will be accessible.
2. If the valve is not closed completely:
   - A. Slightly loosen the set screw on the bottom cam.
   - B. Rotate the cam counter-clockwise (CCW) by hand until the switch makes contact. Contact is made when a slight click can be heard. By making incremental CCW movements of the bottom cam, the valve can be positioned precisely in the desired position.
   - C. When the top cam is set, tighten the set screw securely.
3. If the valve closes too far:
   - A. Apply power to terminals. This will begin to rotate valve CCW. When valve is fully closed and in the exact position desired, remove power from actuator.
   - B. Loosen the set screw in the top cam.
   - C. Rotate the top cam clockwise (CW) until the switch arm drops off the round portion of the cam onto the flat section. A slight click can be heard as the switch is no longer making contact with the round part of the cam.
   - D. Continue applying power to terminals until valve is in the desired position.

### Double Acting Actuator Torque

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### Spring Return Actuator Torque

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### SR Single Acting Pneumatic Actuator Torque (lb-in)

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Wiring Diagrams for TI01-TI10: 120 VAC, TI01-TI10: 220VAC, TI01-TI10: 24 VAC

1 2 3 4 5 6 7 8 9 10

N HOT

A.C. SUPPLY

POWER

PSC MOTOR

CAPACITOR

SW. #2

OPTIONAL BRAKE

SW. #1

CLOSE LIMIT

SW. #2

OPEN LIMIT

SWITCH LAYOUT

NOTES:
POWER TO TERMINALS ONE & TWO OPENS THE VALVE (CCW ROTATION)
POWER TO TERMINALS ONE & THREE CLOSES THE VALVE (CW ROTATION)
TERMINALS 4 & 5 ARE FOR LIGHT INDICATION

WIRING DIAGRAM ILLUSTRATES THE ACTUATOR IN THE OPEN POSITION

OPTIONAL HEATER & THERMOSTAT

GROUND SCREW

FIELD WIRING

LIGHTS FOR REMOTE POSITION INDICATION

OPTIONAL EQUIPMENT FIELD WIRING

Wiring Diagrams for TI01-TI10: 12VDC, TI01-TI10: 24 VDC

12 3 4 5 6

COIL

DC VOLTAGE

REVERSING RELAY SUPPLIED BY CUSTOMER

SPDT SWITCH SHOWN FOR ILLUSTRATION ONLY

FIELD WIRING

OPERATION:
POWER TO 1 & 2 FOR CCW ROTATION
POWER TO 3 & 4 FOR CW ROTATION
TERMINALS 5 & 6 FOR FIELD LIGHT INDICATION CONNECTION

SW. #1

SW. #2

SWITCH #1 OPEN SWITCH
SWITCH #2 CLOSE SWITCH

ACTUATOR SHOWN IN OPEN POSITION
Wiring Diagrams for
MI01-MI10: 120 VAC, MI01-MI10: 220 VAC, MI01-MI10: 24 VAC

NOTE:
ACTUATOR SHIPPED IN OPEN POSITION. 20mA REPRESENTS OPEN POSITION. DO NOT ADJUST FEEDBACK POTENTIOMETER OR LIMIT SWITCHES THEY ARE FACTORY SET AND DO NOT REQUIRE CALIBRATION. TO CALIBRATE THE OPEN AND CLOSE POSITION USE THE ZERO (4mA) AND SPAN (20mA) TRIM POTENTIOMETERS.

TO CALIBRATE OPERATE ACTUATOR TO CLOSE POSITION AND ADJUST WITH ZERO TRIM POT THEN OPERATE TO OPEN POSITION AND SET USING SPAN TRIM POT. NO FUTHER CALIBRATION IS NECESSARY.

OPTIONAL EQUIPMENT
FIELD WIRING

Wiring Diagram for 1Ph/60Hz Electric Actuator with 4-20mA, 0-5Vdc OR 0-10Vdc CONTROL.

JP2 RED GREEN
JP3 JP4
F U S E
DEAD BAND
JP1 ZERO SPAN
C NO NC
C NO NC

JP2 RED GREEN
JP3 JP4 JUMPER SET FOR FAIL OPEN UPON LOSS OF CONTROL SIGNAL
JUMPER AS SHOWN BELOW IS FAIL IN LAST POSITION UPON LOSS OF SIGNAL
JUMPER SET FOR FAIL CLOSE UPON LOSS OF CONTROL SIGNAL
JUMPER AS SHOWN BELOW IS FAIL IN LAST POSITION UPON LOSS OF SIGNAL

NOTE:
ACTUATOR SHIPPED IN OPEN POSITION. 20mA REPRESENTS OPEN POSITION. DO NOT ADJUST FEEDBACK POTENTIOMETER OR LIMIT SWITCHES THEY ARE FACTORY SET AND DO NOT REQUIRE CALIBRATION. TO CALIBRATE THE OPEN AND CLOSE POSITION USE THE ZERO (4mA) AND SPAN (20mA) TRIM POTENTIOMETERS.

TO CALIBRATE OPERATE ACTUATOR TO CLOSE POSITION AND ADJUST WITH ZERO TRIM POT THEN OPERATE TO OPEN POSITION AND SET USING SPAN TRIM POT. NO FUTHER CALIBRATION IS NECESSARY.

OPTIONAL EQUIPMENT
FIELD WIRING

Wiring Diagram for 1Ph/60Hz Electric Actuator with 4-20mA, 0-5Vdc OR 0-10Vdc CONTROL.

JP2 RED GREEN
JP3 JP4
F U S E
DEAD BAND
JP1 ZERO SPAN
C NO NC
C NO NC
To speed up installation of the control wires to the ACT-MDXX modulating actuator, it is recommended to remove the control module from the actuator. The control module can be removed by removing the two mounting screws on the left and right of the control module. Install the control wires to the correct terminal points and then reinstall the control module.

**Electric Actuator Maintenance**

Once the actuator has been properly installed, it requires no maintenance. The gear train has been lubricated and in most cases will never be opened.

**Duty Cycle Definition**

“Duty Cycle” means the starting frequency.

Formula: \( \text{Running Time} - (\text{Running Time} \div \text{Rest Time}) \times 100\% = \text{duty cycle} \)

\[ \Rightarrow \text{Rest Time} = \frac{\text{Running Time} \times (1 - \text{duty cycle})}{\text{duty cycle}} \]

For example: The running time is 15 seconds

- 30% duty cycle \( 15 \times \left[ \frac{(1 - 30\%)}{30\%} \right] = 35 \rightarrow \) The rest time will be 35 seconds

- 75% duty cycle \( 15 \times \left[ \frac{(1 - 75\%)}{75\%} \right] = 5 \rightarrow \) The rest time will be 5 seconds

If the duty cycle is higher, the rest time will be shortened. It means the starting frequency will be higher.

**Thermal Overload**

All actuators are equipped with thermal overload protection to guard the motor against damage due to overheating.

**Mechanical Overload**

All actuators are designed to withstand stall conditions. It is not recommended to subject the unit to repeated stall conditions.

**Explosion-Proof Electric Actuators**

1. DO NOT under any circumstances remove the cover of the actuator while in a hazardous location. Removal of the cover while in a hazardous location could cause ignition of hazardous atmospheres.

2. DO NOT under any circumstances use an explosion-proof electric actuator in a hazardous location that does not meet the specifications for which the actuator was designed.

3. Always verify that all electrical circuits are de-energized before opening the actuator.

4. Always mount and cycle test the actuator on the valve in a non-hazardous location.

5. When removing the cover, care must be taken not to scratch, scar of deform the flame path of the cover and base of the actuator, since this will negate the NEMA rating of the enclosure.

6. When replacing the cover, take care that the gasket is in place to assure proper clearance after the cover is secured.

7. All electrical connections must be in accordance with the specifications for which the unit is being used.

8. Should the unit ever require maintenance, remove from the hazardous location before attempting to work on the unit.

If the actuator is in a critical application, it is advisable to have a standby unit in stock.

**WARNING**

For Electric Actuators Wiring Diagram: ACT-TD & ACT-MD

**Wiring Diagrams for**

- **TD01-TD09: 120 VAC, TD01-TD09: 220 VAC, TD01-TD09: 24 VAC**

**Wiring Diagrams for**

- **MD01-MD09: 120 VAC, MD01-MD09: 220 VAC, MD01-MD09: 24 VAC**
### Electric Actuators Performance Rating

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<th>TD02 and MD02 (MD Not Available in 24 VDC)</th>
<th>TD03 and MD03 (MD Not Available in 24 VDC)</th>
<th>TD04 and MD04 (MD Not Available in 24 VDC)</th>
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<th>TD06 and MD06 (MD Not Available in 24 VDC)</th>
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<tr>
<td>AMP Draw</td>
<td>0.57 A</td>
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<tr>
<td>Torque</td>
<td>1770 in-lb</td>
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<td>1770 in-lb</td>
<td>1770 in-lb</td>
<td>1770 in-lb</td>
<td>100 in-lb</td>
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</tr>
<tr>
<td>Voltage</td>
<td>24 VAC</td>
<td>24 VAC</td>
<td>24 VAC</td>
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<tr>
<td>Cycle Time</td>
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<tr>
<td>Duty Cycle (Two-Position)</td>
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<tr>
<td>Duty Cycle (Modulating)</td>
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<td>AMP Draw</td>
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<tr>
<td>Torque</td>
<td>1770 in-lb</td>
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<td>1770 in-lb</td>
<td>1770 in-lb</td>
<td>100 in-lb</td>
<td>100 in-lb</td>
</tr>
</tbody>
</table>

### MAINTENANCE/REPAIR

Upon final installation of the Series WE, only routine maintenance is required. The Series WE is not field serviceable and should be returned if repair is needed. Field repair should not be attempted and may void warranty.

**WARRANTY/RETURN**

Refer to “Terms and Conditions of Sale” in our catalog and on our website. Contact customer service to receive a Return Goods Authorization number before shipping the product back for repair. Be sure to include a brief description of the problem plus any additional application notes.